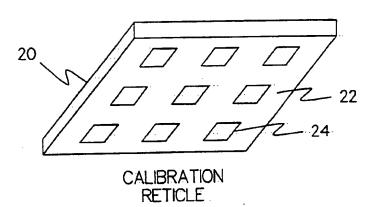
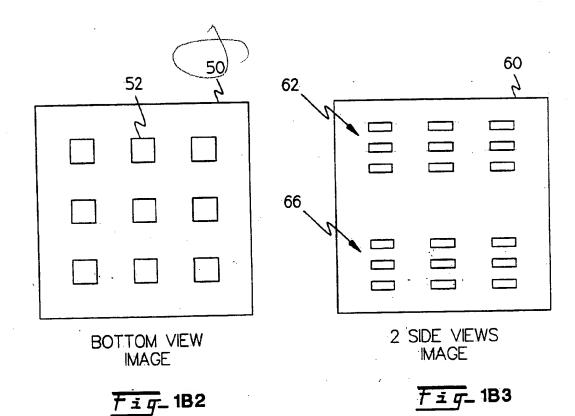
713.

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PUBULASS



† i g_ 1B1

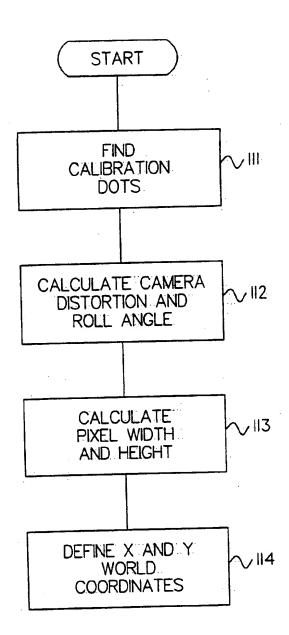


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START 101 PROVIDING A TRANSPARENT RETICLE HAVING A BOTTOM SURFACE WITH A PATTERN OF PRECISION DOTS. \sim 102 PROVIDING A CAMERA DISPOSED BENEATH THE TRANSPARENT RETICLE TO RECEIVE AN IMAGE OF THE DOT PATTERN WHEREIN THE CAMERA PROVIDES THE IMAGE DATA. PROVIDING A FRAME GRABBER BOARD TO RECEIVE THE 1/103 MAGE DATA. \₁04. PROCESSING THE IMAGE DATA WITH A PROCESSOR TO CALCULATE THE STATE VALUES OF THE BOTTOM VIEW.

Fig_2A

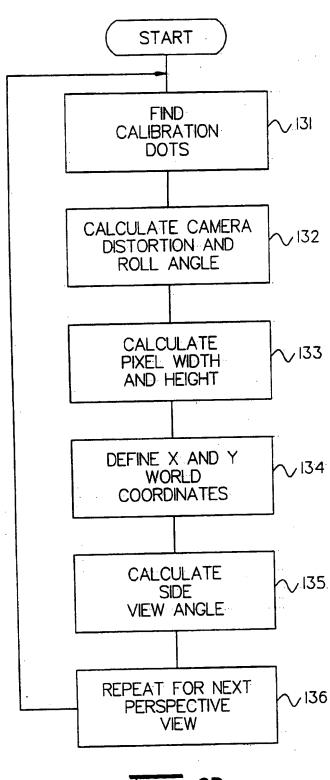
PULCUASS



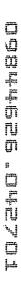
Fig_2B

START PROVIDING A TRANSPARENT RETICLE HAVING A BOTTOM 121 SURFACE WITH A PATTERN OF PRECISION DOTS. //122 PROVIDING FIXED OPTICAL ELEMENTS FOR OBTAINING SIDE PERSPECTIVE VIEWS. $\sqrt{123}$ PROVIDING A CAMERA DISPOSED TO RECEIVE AN IMAGE OF SIDE PERSPECTIVE VIEWS REFLECTED FROM OPTICAL ELEMENTS. PROVIDING A FRAME GRABBER BOARD TO RECEIVE THE IMAGE DATA. 125 PROCESSING THE IMAGE DATA WITH A PROCESSOR TO CALCULATE THE STATE VALUES OF THE SIDE PERSPECTIVE VIEWS.

Fig-20



Fig_2D



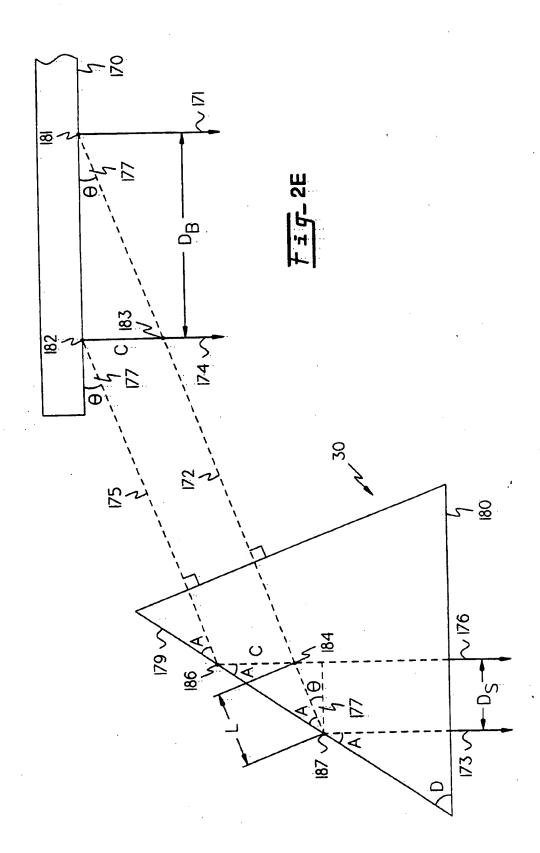
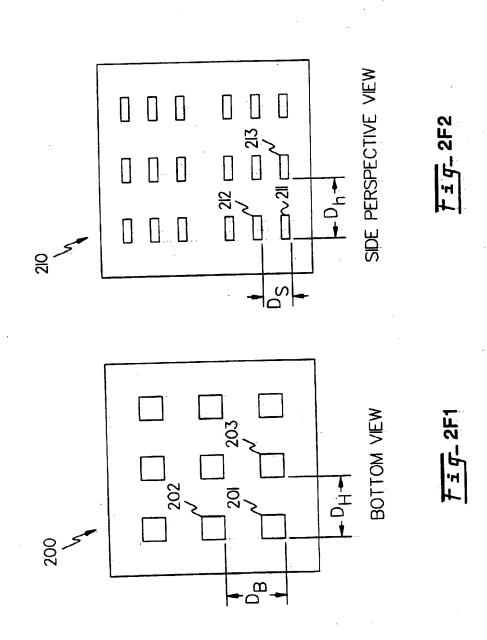
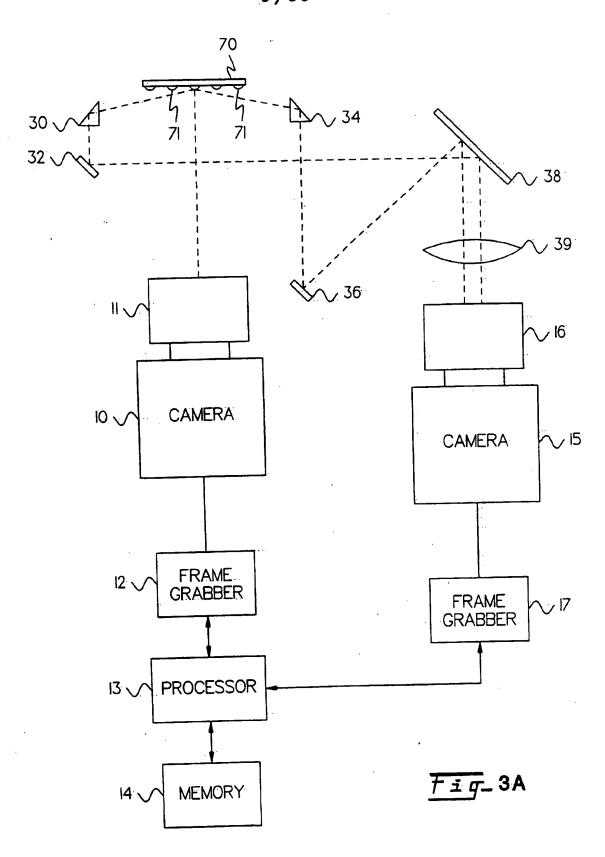
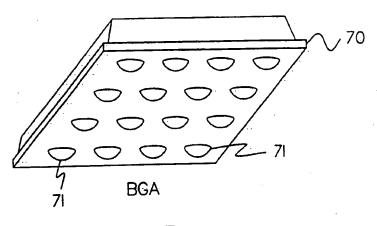


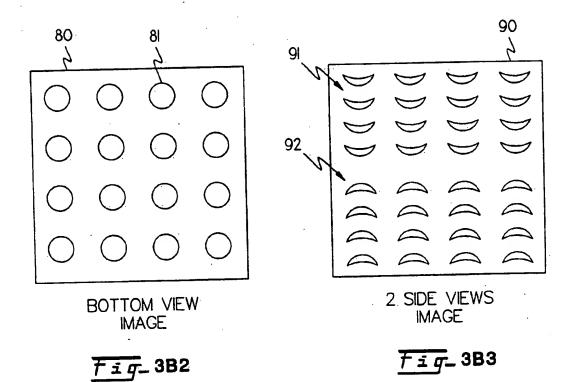
FIG.

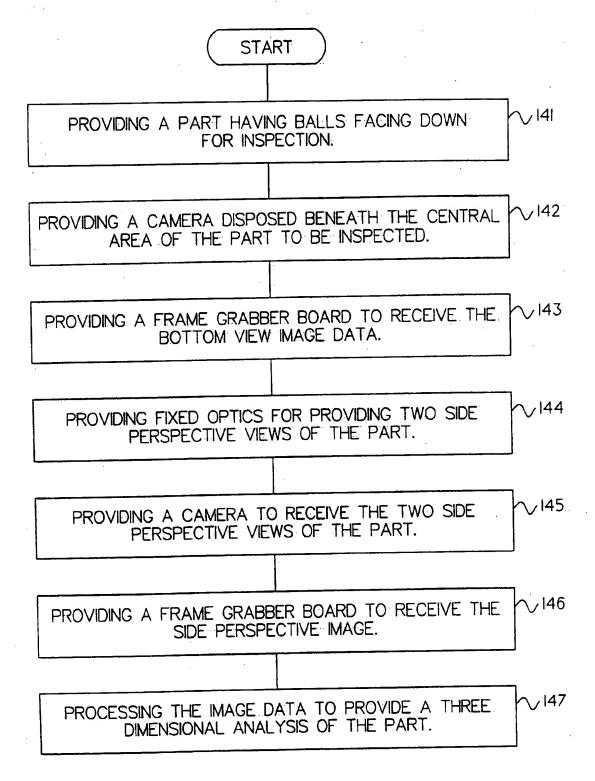






Fig_3B1





Fig_4

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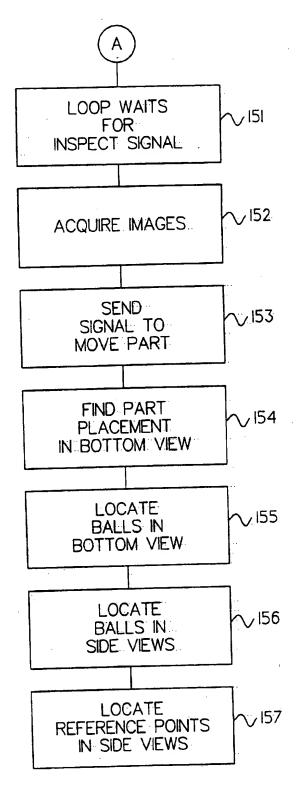
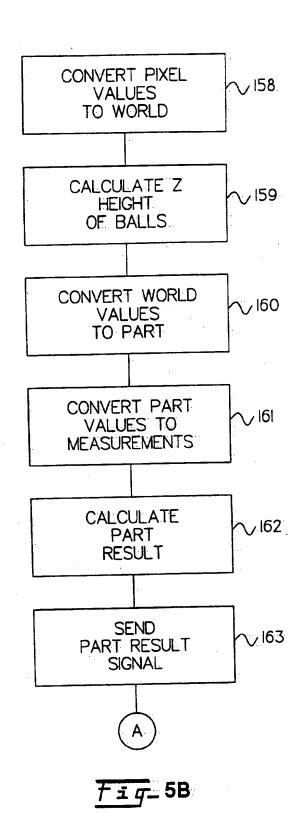
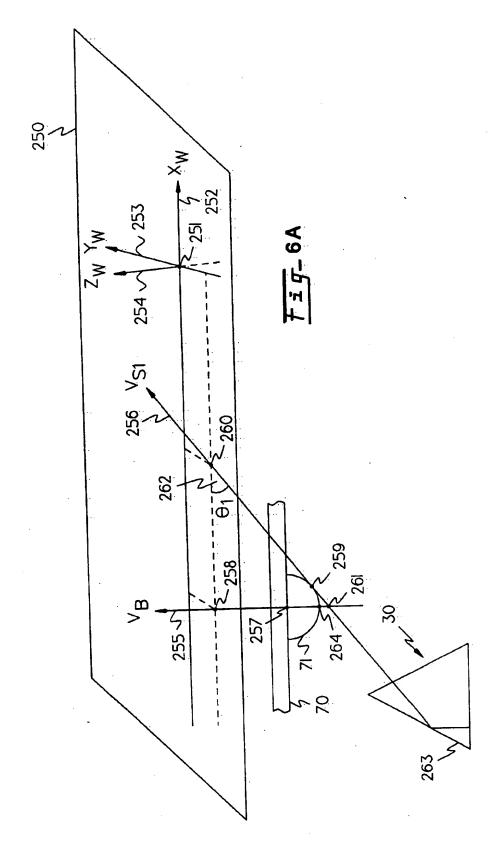
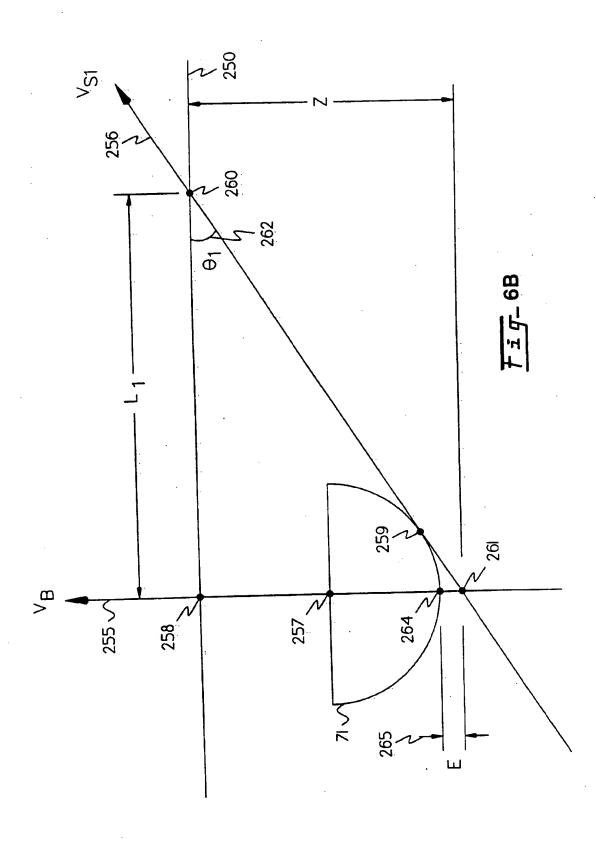


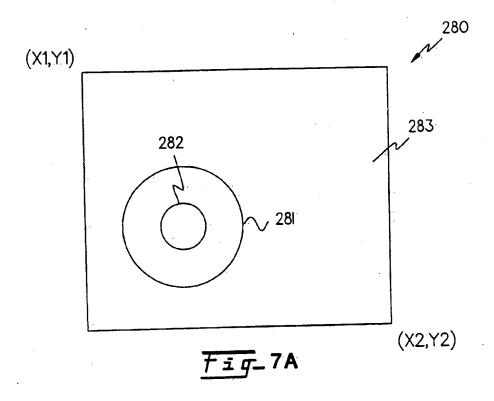
Fig-5A

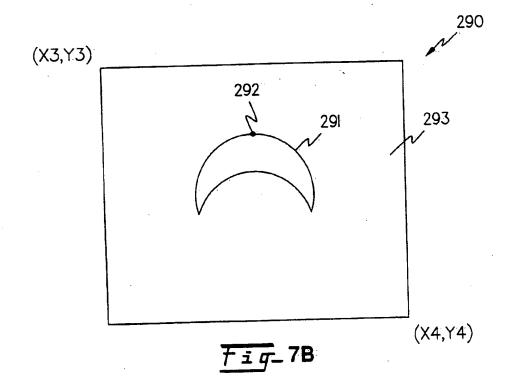


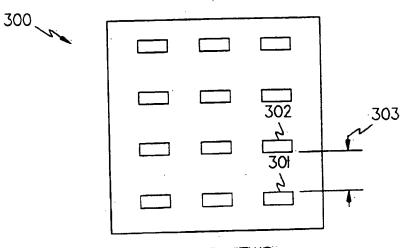


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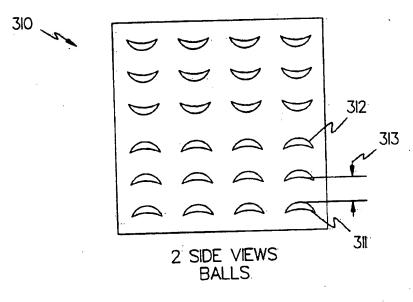




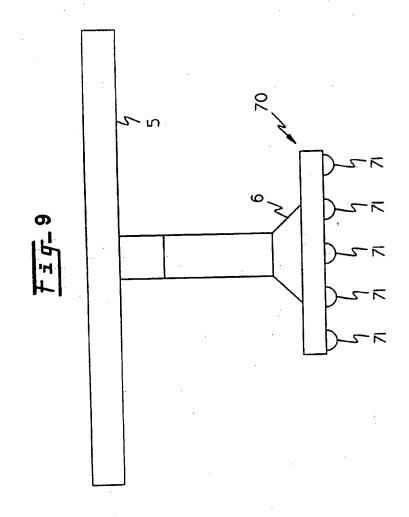


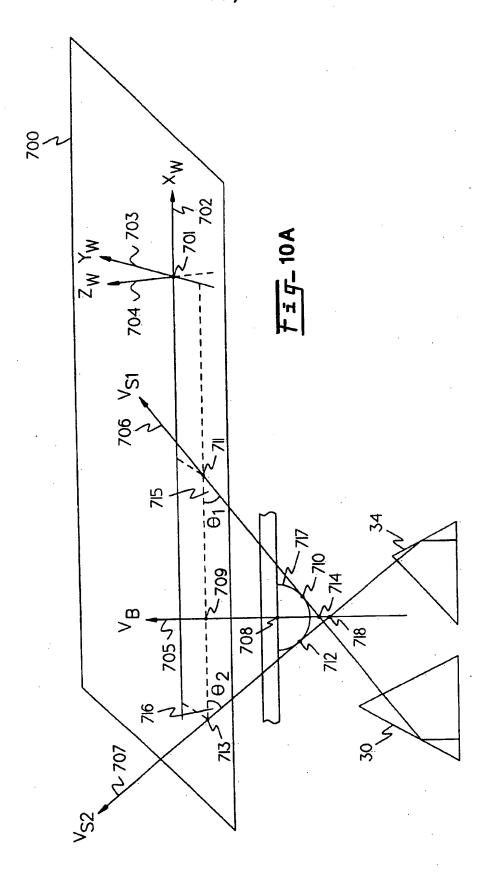
2 SIDE VIEWS CALIBRATION PATTERN

Fig_8A



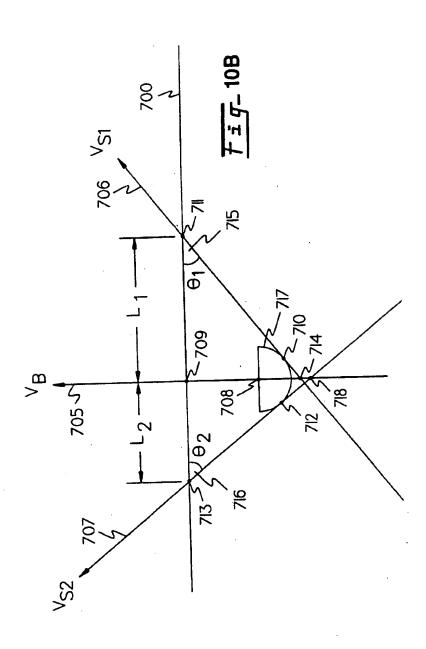
Fig_8B

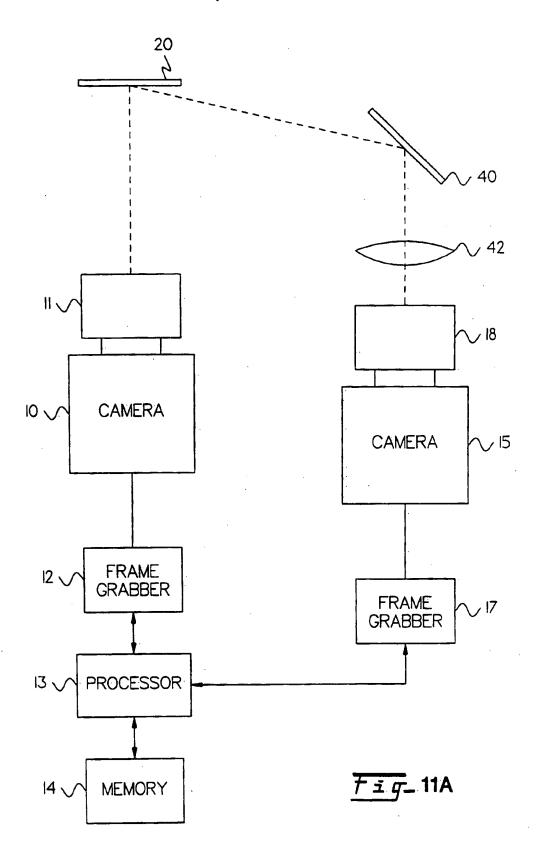


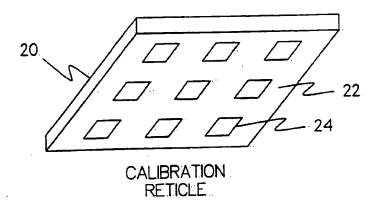


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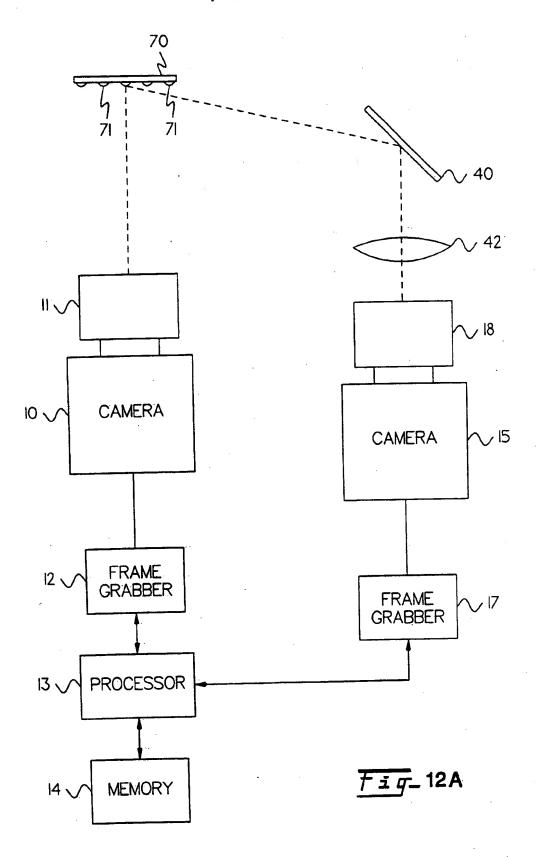
<u>Fig_</u>11B1

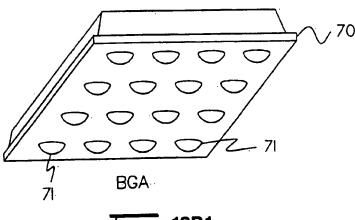
50 52 2	64
	65
BOTTOM VIEW IMAGE	SIDE VIEW IMAGE

Fig_11B2

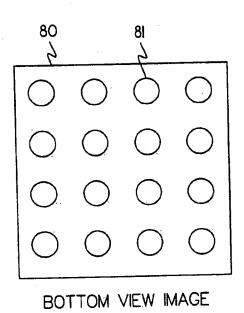
Fig_11B3

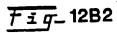


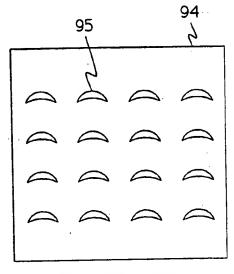




<u>Fig</u>_12B1

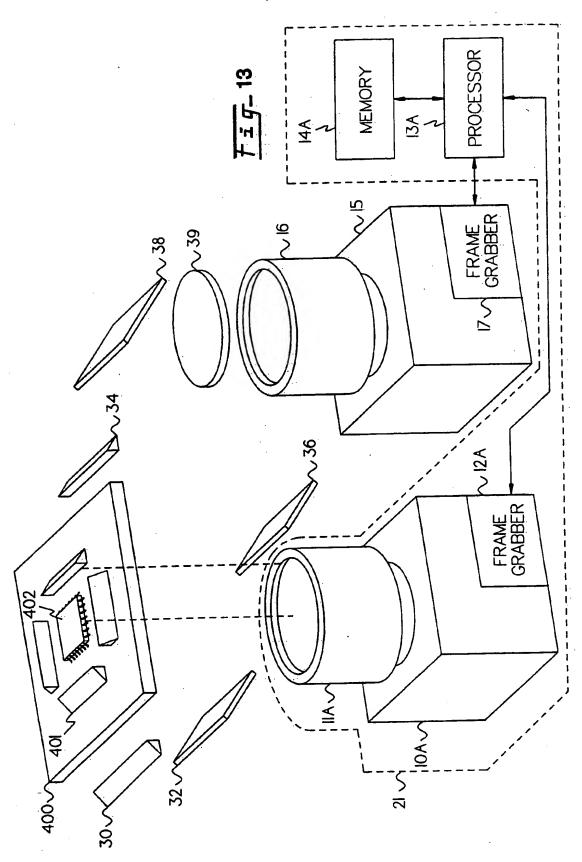


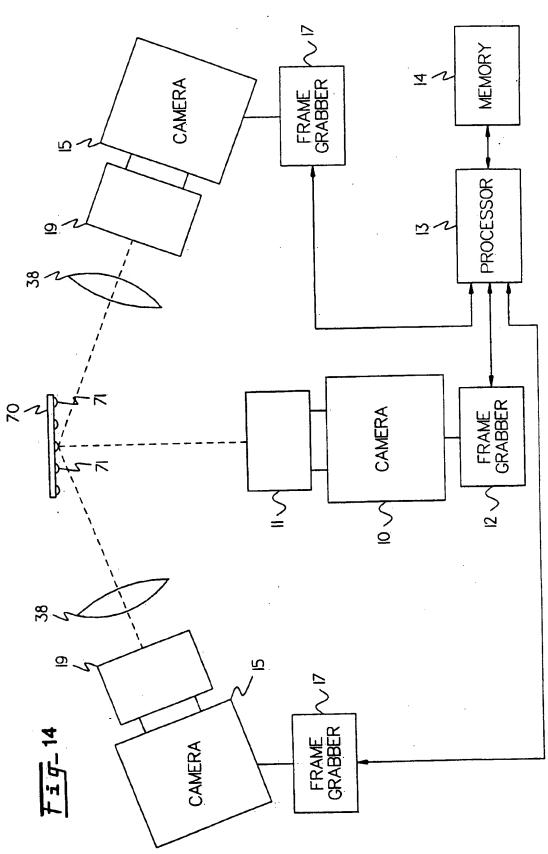


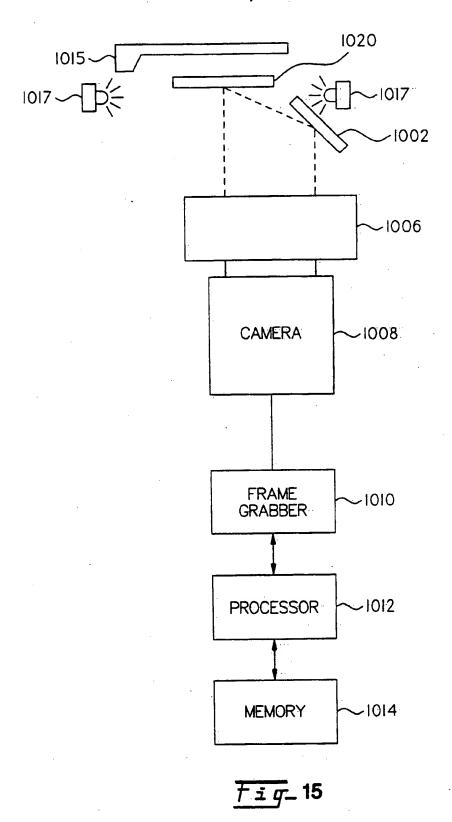


SIDE VIEW IMAGE

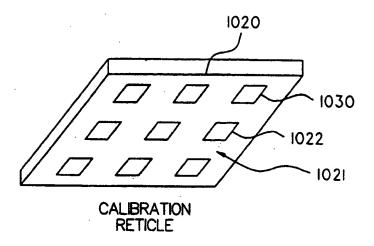
<u>Fig</u>_12B3



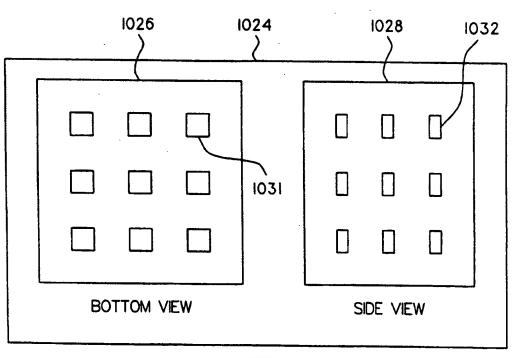




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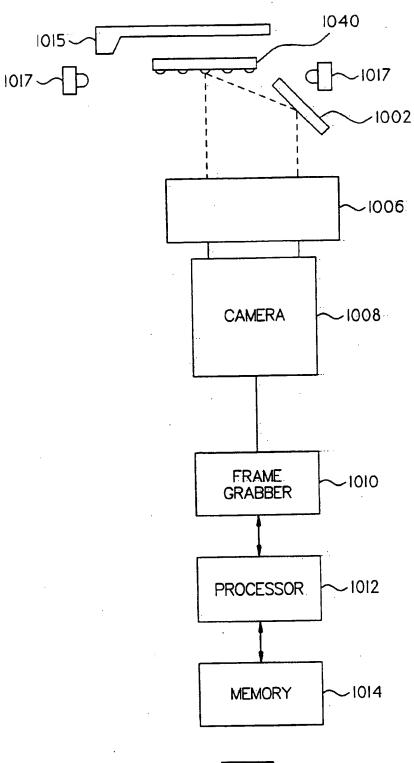


Fig_ 16A



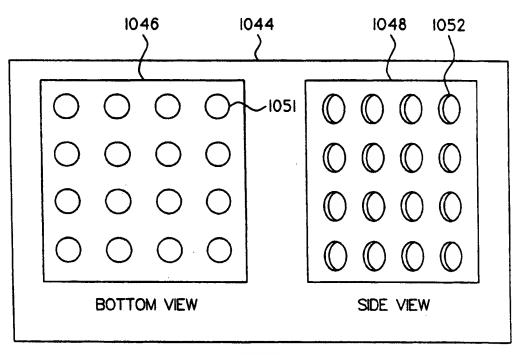
IMAGE

Fig_16B



Fig_17

Fig_18A



IMAGE

J g_ 18B

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